#### **Autonics**

# ROTARY ENCODER (HAND TYPE) **ENH SERIES**

Α A



Thank you very much for selecting Autonics products. For your safety, please read the following before using.

### Caution for your safety

\*Please keep these instructions and review them before using this unit.

\*Please observe the cautions that follow;

**Warning** Serious injury may result if instructions are not followed.

**⚠** Caution

Product may be damaged, or injury may result if instructions are not

\*The following is an explanation of the symbols used in the operation manual. Acaution: Injury or danger may occur under special conditions.

## **⚠** Warning

1. When use this unit for controlling highly affective equipment to human or properties. (Medical instrument, Vehicles, Train, Airplane, combustion apparatus, entertainment etc.), it requires installing a fail safety device. It may cause serious human injury or a fire, property.

# 

1. Do not drop water or oil on this unit.

It may cause damage or miscontrol due to malfunction.

2. Please observe voltage rating.

It may shorten the life cycle or damage to the product.

3. Please check the polarity of power and wrong wiring.

It may result in damage to this unit.

4. Do not short circuit the load.

It may result in damage to this unit.

#### Outline

This Rotary encoder is optical incremental type, these Encoder register position and angular speed determination by counting the number of pluses on the rotary shaft.

# Ordering information

ENH		100		1		T		24	
Ser	Series		lse/ olution	Click stop position		Output		Power supply	
Handle type				1	mal "H" mal "L"	T: Totem pole output V: Voltage output L: Line driver output		5:5VDC ±5% 24:12-24VDC ±5%	

is only for 5VDC

\*The above specification are changeable without notice anytime.

#### Specifications

1			Tamend Specimental Hotaly Shedder					
	Totempole output  Voltage output  Line driver output		ENH1-T, ENH2-T					
М			ltage output	ENH1-V, ENH2-V				
			ENH1-L, ENH2-L					
Re	esolution (P/R)			25P/R, 100P/R(Not indicated type is available to customize)				
	Output phase			A, B phase (Line driver output A, Ā, B, B̄ phase)				
	Phase difference of output			Output between A and B phase : $\frac{T}{4} \pm \frac{T}{8}$ (T=1cycle of A phase)				
	Control output		Totempole output	Low  Load current: Max. 30mA, Residual voltage: Max. 0.4VDC     High  Load current: Max. 10mA,     Output voltage(Power supply 5VDC): Min. (Power supply-2.0)VDC,     Output voltage(Power supply 12-24VDC): Min. (Power supply-3.0)VDC				
<u>_</u>			Voltage output	Load current:Max. 10mA, Residual voltage:Max. 0.4VDC				
Electrical specification			Line driver output	<ul> <li>Low ☞ Load current:Max. 20mA, Residual:Max. 0.5V</li> <li>High ☞ Load current:Max20mA, Output voltage:Min. 2.5V</li> </ul>				
eci	Respons		Totempole output		Max. 1μs	Measuring condition		
Sp		me	Voltage output	Max. 1μs		Cable length:1m,		
ica	(Rise & Fa		Line driver output	Max. 0.2 <i>µ</i> s		I sink=Max. 20mA		
ectr	Power supply		Totempole output	• 5VDC ±5%(Ripple P-P:Max. 5%)				
m			Voltage output	• 12-24VDC $\pm$ 5%(Ripple P-P:Max. 5%)				
			Line driver output	5VDC ±5%(Ripple P-P:Max. 5%)				
	Current consumption			Max. 40mA(disconnection of the load), Line driver output:Max. 50mA(disconnection of the load)				
	Max. Response frequency			10kHz				
	Insulation resistance			Min. 100№(at 500VDC between all terminals and case)				
	Dielectric strength			750VAC 50/60Hz for 1 minute(Between all terminals and case)				
	Connection			Terminal block type				
	echanical Shaft Ic		Starting torque	Max. 1kgf • cm(0.098N • m)				
1			Shaft loading	Radial:2kgf, Thrust:1kgf				
30			Mechanical revolution	(Note1) Max. 200rpm(Normal), 600rpm(Peak)				
Vibration				1.5mm amplitude at frequency of 10~55Hz in each of X, Y, Z directions for 2 hours				
Shock				Max. 50G				
An	mbient temperature			-10~70℃(at non-freezing status), Storage:-25~85℃				
An	nbient	humi	idity	35~85%RH, Storage: 35~90%RH				
Pr	otection			IP50(IEC standard)				
We	Weight			Approx. 300g				
* (Note1) Max. allowable revolution ≥ Max. response revolution								

Handle type Incremental Botary encoder

 $\times$  (Note1) Max. allowable revolution  $\geq$  Max. response revolution

 $\frac{\text{Max. response frequency}}{\text{Max. second}} \times 60 \text{ second}$ [Max\_response revolution(rpm)= Resolution

Please select the resolution to make lower max. revolution than max. allowable revolution

# Dimensions $3-M4 \times 0.7$ L=10 ø 77 P.C.D 72 $\phi 59.8^{-0}$ (Unit:mm) $\phi$ 80 $\pm$ 0.1 ※P.C.D ø70mm : Option

### Control output diagram

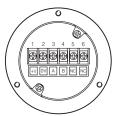
Totem po	ole output	Voltage	e output	Line driver output		
Rotary encoder circuit Load connection		Rotary encoder circuit	Load connection	Rotary encoder circuit	Load connection	
Sink curr Max. 30n	Output +	Main circuit	Source current: Max. 10mA Output + Load 0V	Main circuit	A phase output + A phase output - OV	

The output circuit of A, B, Z phase are the same. (Line Driver output is A, A, B, B, Z, Z)

Totem pole output can be used for NPN open collector type(\*1) or voltage output type(\*2).

#### Connections

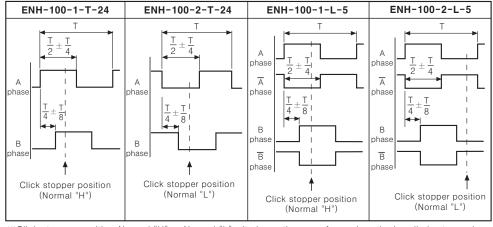
Totempole output / Voltage output



Line driver output

\*Do not use terminals 5 and 6.

## Output waveform



\*Click stopper position Normal "H" or Normal "L": It shows the wave form when the handle is stopped.

#### Caution for using

1. Installation

1)This unit is consisted of precision components.

Therefore please treat this product carefully

②Panel for installing this unit should be good earth ground.

③When the surge occurred in power source, please install a surge absorber for removing surae

2. For using

①Please use attached Sil Twist pair wire and use proper receiver for RS-422A communication.

②Do not connect and cut circuit off during power on. It may result in damage to this unit.

Please do not use this unit with below environment, it results in malfunction.

①Place where strong magnet field or electric noise are occurred.

②Place where is beyond of rating temperature or humidity.

4. Vibration and Impact

①Do not put strong impact when mount this unit on panel.

②Please fix this unit firmly when mount it in order to avoid malfunction by residual vibration.

5 Wire connection

①If use the cable of encoder and high voltage line or power cable in the same conduit, it may cause a malfunction or mechanical trouble. Please wire separately or use separated conduit

②Please make the cable as shorter as it can be in order to avoid noise affection.

③Please fix terminal block firmly for not escaped when pull the wire from terminal block with

\*It may cause malfunction if above instructions are not followed.

#### Major products

■ PROXIMITY SENSOR ■ PHOTOELECTRIC SENSOR

■ AREA SENSOR ■ FIBER OPTIC SENSOR

■ DOOR/DOOR SIDE SENSOR

■ PRESSURE SENSOR

■ ROTARY ENCODER ■ COUNTER

■ TIMER ■ TEMPERATURE CONTROLLER

■ TEMPERATURE/HUMIDITY TRANSDUCER

■ POWER CONTROLLER ■ PANEL METER

■ TACHO/LINE SPEED/PULSE METER

■ DISPLAY UNIT ■ SENSOR CONTROLLER

■ SWITCHING POWER SUPPLY

■ GRAPHIC PANEL

■ 5-PHASE STEPPING MOTOR & DRIVER & CONTROLLER

■ LASER MARKING SYSTEM(CO2, Nd:YAG)

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